

# Matrix Algebra

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$$A_{m \times n}$$

"Rectangular Array"

$m$  rows  
 $n$  columns

with typical element  $A_{ij}$

$i^{\text{th}}$  row  
 $j^{\text{th}}$  column.

A vector is a matrix that has only 1 column or 1 row.

$$A = \begin{matrix} 2 & 3 \\ 6 & 2 \\ 1 & 5 \end{matrix} = \{ \underset{\sim}{a_1} \quad \underset{\sim}{a_2} \}$$

$$\underset{\sim}{a_1} = \begin{pmatrix} 2 \\ 6 \\ 1 \end{pmatrix} \quad \underset{\sim}{a_2} = \begin{pmatrix} 3 \\ 2 \\ 5 \end{pmatrix}$$

$$\text{or } A = \begin{matrix} \underset{\sim}{a_1} \\ \underset{\sim}{a_2} \end{matrix}$$

$\underset{\sim}{a_1}$  &  $\underset{\sim}{a_2}$  are column vectors  
 $3 \times 1$

Square matrix has same # of rows or columns i.e.,  $m = n$

If a matrix is symmetric  $A_{ij} = A_{ji}$  for all  $i, j$ . Note, only possible for square matrices.

A diagonal matrix has zeros on all elements of  $A_{ij}$   $i \neq j$

$$A = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

The principal diagonal is the nonzero entries  $A_{ij}$   $i = j$

If entries above the diagonal are zero

$$A_1 = \begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 7 & 3 & 2 \end{pmatrix} \text{ lower triangular}$$

A transpose of a matrix interchanges  
rows & columns

$$B = \begin{matrix} & & & \\ & & & \\ & & & \\ 2 \times 3 & \begin{pmatrix} 2 & 3 & 1 \\ 5 & 7 & 9 \end{pmatrix} & & \end{matrix}$$

$$B^T = \begin{matrix} & & & \\ & & & \\ & & & \\ 3 \times 2 & \begin{pmatrix} 2 & 5 \\ 3 & 7 \\ 1 & 9 \end{pmatrix} & & \end{matrix}$$

Symmetric matrices  $A = A^T$

### Operations

~~At~~ Matrices can be added & subtracted only if they are conformable. They must have the same row & column dimensions.

$A + B$  has typical element  $A_{ij} + B_{ij}$

$A - B$  " " "  $A_{ij} - B_{ij}$

$$A = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} \quad B = \begin{pmatrix} 2 \\ 7 \\ 5 \end{pmatrix} \quad A+B = \begin{pmatrix} 3+2 \\ 2+7 \\ 1+5 \end{pmatrix}$$

## Multiplication

This involves what is called  
scalar product or inner product.

Take 2  $n$  vectors  $\underline{a}$  and  $\underline{b}$ .

$$\underline{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_n \end{pmatrix} \quad \underline{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

The scalar product is denoted

$$\underline{a}^T \underline{b} = \sum_{i=1}^n a_i b_i$$

$$\left( \begin{matrix} a_1 & a_2 & \dots & a_n \end{matrix} \right) \left( \begin{matrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{matrix} \right) = a_1 b_1 + a_2 b_2 + \dots + a_n b_n$$

## Two Matrices

$$A$$

$$n \times m$$

$$B_{m \times p}$$

$$A \cdot B = C$$

$$\begin{array}{ccc} n \times m & m \times p & n \times p \\ \downarrow & & \end{array}$$

Take scalar product of each row of A  
times each column of B

The column dimension of the first  
matrix MUST = Row dim of B.

$$C_{ij} = \sum_{k=1}^m A_{ik} B_{kj}$$

$$A = \begin{pmatrix} 2 & 3 & 3 \\ 1 & 7 & 2 \end{pmatrix}$$

$$B = \begin{pmatrix} -1 & 2 \\ 0 & 3 \\ 1 & -2 \end{pmatrix}$$

$$A \cdot B =$$

$$2(-1) + 3(0) + 3(1)$$

$$1(-1) + 7(0) + 2(1)$$

$$1(2) + 7(3) + 2(-2)$$

$$2(2) + 3(3) + 3(-2)$$

Given these rules it is generally  
True that

$$A \cdot B \neq B \cdot A$$

Identity

$A$   
 $m \times n$

$$A \cdot I_m = A$$

$$I_m \cdot A = A$$

$$I_n = \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & \\ 0 & \cdots & 0 & 1 & \\ \vdots & & & & \ddots \\ 0 & \cdots & 0 & 0 & 1 \end{bmatrix}$$

$I$  is a <sup>diagonal</sup> matrix with 1 along principal diag.

One vector

$\mathbb{R}^n$

$$\vec{u}_n^T = \begin{pmatrix} 1 \\ 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix}$$

$T \times 1$  vector of 1's

note  $\vec{u}_n^T \vec{b}_n = \sum_{i=1}^n b_i$

## Properties

$$A(B+C) = AB + AC$$

distributive  
with addition.

$$A+B+C = (A+B)+C = A+(B+C)$$

$$(AB)C = A(BC)$$

Associative.

$$(AB)^T = B^T A^T$$

$$(ABC)^T = C^T B^T A^T$$

$A$   
 $m \times n$

Then

$A^T A$  is symmetric  
 $n \times n$

$$\begin{aligned} \text{If symmetric } A^T A &= (A^T A)^T \\ &= A^T (A^T)^T = A^T A \end{aligned}$$

$$\text{Also } A A^T = (A A^T)^T = A A^T$$

Scalar mult.

$$\alpha \cdot A_{m \times n} = \begin{matrix} \alpha A_{11} & \alpha A_{12} & \dots & \alpha A_{1n} \\ \vdots & & & \\ \alpha A_{m1} & \dots & \dots & \alpha A_{mn} \end{matrix}$$

$$\Rightarrow \alpha \cdot A = A \cdot \alpha$$

Element By Element mult. (element product)

$A$  &  $B$  must be same dimension  
 then the typical element is

$$A_{ij} B_{ij}$$

Inverse

$$A \cdot A^{-1} = I \quad A^{-1} \cdot A = I.$$

$A$  must be square and invertible.

If  $A$  is symmetric, so is  $A^{-1}$

If  $A$  is triangular, so is  $A^{-1}$

If  $A$  is diagonal, so is  $A^{-1}$

If a square matrix  $A$  is invertible,  
 then its Rank is  $n$ . Full Rank.

If it is not invertible it is  
 singular and has Rank less than  $n$ .

For non square matrices, the rank is  
 the largest number,  $m$  for which  
 an  $m \times m$  nonsingular matrix  
 can be found by omitting some rows  
 or columns.

Suppose  $X_{T \times K}$   $K \leq T$

Best square matrix is  $K$  dim.

If Rank is  $K$  then it.

$X^T X$  has Rank  $(X^T X) = K$ .  
 $K \times K$

And its inverse will exist.

## Regression Model in Matrix form

$$y_1 = \beta_1 + \beta_2 x_1 + u_1$$

$$y_2 = \beta_1 + \beta_2 x_2 + u_2$$

$$\vdots$$

$$y_n = \beta_1 + \beta_2 x_n + u_n$$

$$\vec{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} \quad X = \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix} \quad \vec{\beta} = \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix}$$

$$\vec{u} = \begin{pmatrix} u_1 \\ \vdots \\ u_n \end{pmatrix}$$

$$\vec{y} = X\vec{\beta} + \vec{u}$$

$y =$  Regressand or dependent var

$X =$  Regressors.

If you have  $k$  regressor

$$X = \begin{bmatrix} \tilde{x}_1 & \tilde{x}_2 & \tilde{x}_3 & \dots & \tilde{x}_k \end{bmatrix}$$

$$= \begin{pmatrix} 1 & x_{12} & x_{13} & \dots & x_{1k} \\ 1 & x_{22} & x_{23} & \dots & x_{2k} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n2} & & & x_{nk} \end{pmatrix}$$

$$\beta = \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_k \end{pmatrix}$$

## MOM

Basic MOM estimation estimates parameters by equating population moments to sample moments.

$$E(Y) = \mu_y = \frac{1}{n} \sum_{i=1}^n y_i$$

## Regression

$$y = X\beta + u \quad \text{or} \quad y_t = \gamma_t^T \beta + u_t$$

$E(u_t | \gamma_t) = 0 \Rightarrow$  by L.I.E.

$$E(X^T u) = 0$$

$t = 1, \dots, n$

$$\frac{1}{n} \sum_{t=1}^n X_t (y_t - \gamma_t^T \beta) = 0$$

$$\sum \gamma_t y_t - \sum \gamma_t \gamma_t^T \beta = 0$$

$$\sum \gamma_t \gamma_t^T \beta = \sum \gamma_t y_t$$

$$\hat{\beta} = \left( \sum_{t=1}^n \gamma_t \gamma_t^T \right)^{-1} \sum_{t=1}^n \gamma_t y_t$$

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

# Least Squares

$$\underset{\sim}{y} = \underset{\sim}{x} \underset{\sim}{\beta} + \underset{\sim}{\epsilon} \quad \text{or}$$

$$y_t = x_t^T \beta + \mu_t \quad t = 1, \dots, n$$

$$\sum_{t=1}^T \mu_t^2 = \sum_{t=1}^T (y_t - x_t^T \beta)^2$$

$$\begin{aligned} SSR(\mu) = \underset{\sim}{\mu}' \underset{\sim}{\mu} &= (\underset{\sim}{y} - \underset{\sim}{x} \beta)^T (\underset{\sim}{y} - \underset{\sim}{x} \beta) \\ &= \underset{\sim}{y}' \underset{\sim}{y} - \underset{\sim}{y}' \underset{\sim}{x} \beta - \beta^T \underset{\sim}{x}' \underset{\sim}{y} + \beta^T \underset{\sim}{x}' \underset{\sim}{x} \beta \end{aligned}$$

$$\begin{aligned} \frac{\partial S}{\partial \beta} &= \underset{\sim}{x}' \underset{\sim}{y} - \underset{\sim}{x}' \underset{\sim}{y} + 2 \underset{\sim}{x}' \underset{\sim}{x} \beta \\ &= -2 \underset{\sim}{x}' \underset{\sim}{y} + 2 \underset{\sim}{x}' \underset{\sim}{x} \beta = 0 \end{aligned}$$

$$\underset{\sim}{x}' \underset{\sim}{x} \hat{\beta} = \underset{\sim}{x}' \underset{\sim}{y}$$

$$(\underset{\sim}{x}' \underset{\sim}{x})^{-1} \underset{\sim}{x}' \underset{\sim}{y} = \hat{\beta} \quad OLS$$

$$\text{Let } y = f(x_1, \dots, x_n) \quad \begin{matrix} x_1 \\ \vdots \\ x_n \end{matrix}$$

$$\text{or } y = f(\underline{x}) \quad \underline{x} = \begin{matrix} x_1 \\ \vdots \\ x_n \end{matrix}$$

$$\frac{dy}{d\underline{x}} = \begin{pmatrix} \partial y / \partial x_1 \\ \partial y / \partial x_2 \\ \vdots \\ \partial y / \partial x_n \end{pmatrix} \quad n \times 1$$

$$\text{If } X_{n \times m} \quad \text{and} \quad y = f(X)$$

$$\frac{dy}{dX_{n \times m}} = \begin{pmatrix} \partial y / \partial x_{11} & \partial y / \partial x_{12} & \dots & \partial y / \partial x_{1n} \\ \vdots & \vdots & & \vdots \\ \partial y / \partial x_{n1} & \dots & & \partial y / \partial x_{nm} \end{pmatrix} \quad n \times m$$

Let  $y$   $n \times 1$  and  $x$   $n \times 1$

$$\frac{\partial y}{\partial x^T} = \begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \dots & \frac{\partial y_1}{\partial x_n} \\ \frac{\partial y_2}{\partial x_1} & \dots & \frac{\partial y_2}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial y_m}{\partial x_1} & \dots & \frac{\partial y_m}{\partial x_n} \end{pmatrix}$$

$\frac{\partial^2 y}{\partial x \partial x^T}$   $n \times n$   $\leftarrow$  scalar

$$= \begin{pmatrix} \frac{\partial^2 y}{\partial x_1 \partial x_1} & \frac{\partial^2 y}{\partial x_1 \partial x_2} & \dots & \frac{\partial^2 y}{\partial x_1 \partial x_n} \\ \vdots & \vdots & & \vdots \\ \frac{\partial^2 y}{\partial x_n \partial x_1} & \dots & \dots & \frac{\partial^2 y}{\partial x_n \partial x_n} \end{pmatrix}$$

$$\frac{\partial}{\partial x} \left( \frac{\partial y}{\partial x} \right)_{n \times 1} = \frac{\partial}{\partial x} \begin{pmatrix} \frac{\partial y}{\partial x_1} \\ \frac{\partial y}{\partial x_2} \\ \vdots \\ \frac{\partial y}{\partial x_n} \end{pmatrix} \bigg/ \frac{\partial x^T}{n}$$

Let  $\underline{c}$  be a  $n \times 1$  vector that  
does not depend on  $\underline{x}$

$$\underline{z} = \underline{c}^T \underline{x}$$

$1 \times n \quad n \times 1$

$$\frac{d\underline{z}}{d\underline{x}} = \frac{d\underline{c}^T \underline{x}}{d\underline{x}} = \frac{d}{d\underline{x}} \underline{x}^T \underline{c} = \underline{c}$$

$n \times 1$

$\underline{z}$  is scalar,  $\underline{x}$  is  $n \times 1 \Rightarrow$  result  $n \times 1$

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Let  $C$  be  $n \times m$ ,  $\underline{x}$   $n \times 1$

$$\underline{z} = C \underline{x}$$

~~$n \times n$~~   $n \times 1$   
 $n \times n$   
 $m \times 1$

$$\frac{d\underline{z}}{d\underline{x}^T} = \frac{dC \underline{x}}{d\underline{x}^T}$$

$n \times n$   
 $n \times 1$   
 $n \times n$

$$\frac{d\underline{z}}{d\underline{x}^T} = C^T$$

$n \times n$

$$\frac{d\underline{x}^T C}{d\underline{x}} = C$$

$1 \times n \quad n \times m$   
 $1 \times n$   
 $n \times m$

Let  $A$  be square

$$z = \underline{x}^T A \underline{x}$$

$$\frac{\partial z}{\partial \underline{x}} = A^T \underline{x} + A \underline{x} = (A^T + A) \underline{x}$$

If  $A$  symmetric  $= 2A \underline{x}$