

Model: All variation is captured in the Error Term.

$$y_{it} = \sum_{k=1}^K \beta_k F_{kit} + e_{it} \quad \begin{matrix} i = 1, \dots, N \\ t = 1, \dots, T \end{matrix}$$

Note:  $\beta$  is the same for each individual in every time period. If any differences occur, they must be captured in the error term.

Individual  $i$

$$y_i = X_i \beta + e_i \quad i = 1, \dots, N$$

$$y_i = (y_{i1}, y_{i2}, \dots, y_{iT})'$$

$$X_i = \begin{bmatrix} 1 & F_{2i1} & F_{3i1} & \dots & F_{ki1} \\ 1 & F_{2i2} & F_{3i2} & \dots & F_{ki2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & F_{2iT} & F_{3iT} & \dots & F_{kiT} \end{bmatrix} \quad e_i = \begin{bmatrix} e_{i1} \\ \vdots \\ e_{iT} \end{bmatrix}$$

$$\beta = [\beta_1, \beta_2, \dots, \beta_k]'$$

System

$$\begin{bmatrix} y_1 \\ \vdots \\ y_2 \\ \vdots \\ \vdots \\ y_N \end{bmatrix} = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ \vdots \\ X_N \end{bmatrix} \begin{bmatrix} \beta \\ \vdots \\ \beta \end{bmatrix} + e \quad \Rightarrow \quad \underset{\substack{\text{N} \times \text{N} \\ \text{N} \times \text{K}}}{y} = \underset{\substack{\text{N} \times \text{K}}}{X} \underset{\substack{\text{K} \times 1}}{\beta} + \underset{\substack{\text{N} \times 1}}{e}$$

$$E(ee') = \Sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \dots & \sigma_{1N} \\ \sigma_{21} & \sigma_{22} & & \vdots \\ \vdots & & \ddots & \vdots \\ \sigma_{N1} & & & \sigma_{NN} \end{bmatrix} \quad \begin{matrix} \sigma_{ii} = E(e_i e_i') \\ \sigma_{ij} = E(e_i e_j') \end{matrix}$$

Errors can be related in 3 ways

- (1) Error variance is different for each unit (Hetero)
- (2) Errors are contemporaneously related across units
- (3) Errors are related to one another across time.

These lead to the following Assumptions

$$(1) E(e_{it} e_{it}') = \sigma_i^2 = \sigma_{ii} \quad \forall t$$

$$(2) E(e_{it} e_{jt}') = \sigma_{ij} \quad i \neq j$$

$$a \quad E(e_{it} e_{is}') = \sigma_{ij} \quad \text{if } i=j$$
$$0 \quad \text{if } i \neq j$$

$$(3) e_{it} = \rho e_{it-1} + u_{it}$$

$$E(u_{it}) = 0$$

$$E[u_{it} u_{jt}'] = \begin{cases} \sigma_{ij} & s=t \\ 0 & s \neq t \end{cases}$$

Now, Figure out what  $\Rightarrow$  looks like, estimate it, AND Then do FGLS.

- (1) state  $e_{it}$  in (3) above in terms of  $u_{it}$

$$e_{it} = \rho e_{it-1} + u_{it} \quad e_{it-1} = \rho e_{it-2} + u_{it-1}$$

$$e_{it} = u_{it} + \rho u_{it-1} + \rho^2 e_{it-2}$$

$$e_{it} = \sum_{j=0}^{\infty} \rho^j u_{it-j} + \rho^{j+1} e_{it-j-1}$$

$$e_{it} = \sum_{j=0}^{\infty} \rho^j u_{it-j} \quad \text{if } |\rho| < 1$$

(2) calculate (2) based on result above

$$E(e_{it} e_{jt}) = E\left(\sum_{s=0}^{\infty} \rho_i^s u_{i,t-s} \cdot \sum_{w=0}^{\infty} \rho_j^w u_{j,t-w}\right)$$

$$\sigma_{ij} = E\left[\sum_{s=0}^{\infty} \rho_i^s \rho_j^s (u_{i,t-s})(u_{j,t-w})\right] + \text{C.P.T.} \\ \text{= 0} \\ \text{By (3) above}$$

$$= \phi_{ij} \sum_{s=0}^{\infty} \rho_i^s \rho_j^s$$

$$= \phi_{ij} \sum_{s=0}^{\infty} (\rho_i \rho_j)^s \quad \text{if } |\rho_i \rho_j| < 1 \text{ Then}$$

$$\sigma_{ij} = \phi_{ij} \cdot \frac{1}{1 - \rho_i \rho_j}$$

$$\bar{e}_{it} \cdot e_{jt+s} = E\left[\sum_{s=0}^{\infty} \rho_i^s u_{i,t-s} \sum_{w=0}^{\infty} \rho_j^w u_{j,t+s-w}\right]$$

$$= \rho_j^s \frac{\phi_{ij}}{1 - \rho_i \rho_j}$$

since  $e_{i,t+s}$  is related to  $e_{j,t}$ . By factor  $\rho_j^s$

$$\Omega_{ij} = \frac{\phi_{ij}}{1 - \rho_i \rho_j} \begin{bmatrix} 1 & \rho_j & & & \rho_j^{T-1} \\ \rho_i & 1 & & & \\ \rho_i^2 & & 1 & & \\ \rho_i^{T-1} & \rho_i^{T-2} & \dots & & 1 \end{bmatrix}$$

note:  $\Omega_{ij}$  is NOT symmetric.

### Estimation

1. First, eliminate AR(1), try using P-W Transformation.

$$\rho_i = \begin{bmatrix} \sqrt{1-\rho_i^2} & & & \\ -\rho_i & 1 & & \\ & & -\rho_i & 1 \\ & & & \dots \\ & & & & -\rho_i & 1 \end{bmatrix}$$

$$\rho_i' y = \rho_i' x \beta + \rho_i' e$$

$$\rho_i' e = \begin{bmatrix} \sqrt{1-\rho_i^2} e_{it} \\ u_{it} \\ u_{it} \\ \dots \\ u_{it} \end{bmatrix}$$

$$E [P: e:] = \begin{bmatrix} E \sqrt{1-\rho^2} e_1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ \rho \end{bmatrix}$$

Proof:

$$\begin{aligned} \text{Var } e^2 &= E \left( \sqrt{1-\rho^2} e_1 e_1' \sqrt{1-\rho^2} \right) = E (1-\rho^2) e_1^2 = 1-\rho^2 \cdot \sigma_e^2 \\ &= \frac{1-\rho^2 \cdot \sigma_v^2}{1-\rho^2} = \sigma_v^2 \end{aligned}$$

$$E (e_1 e_{1+j}) = 0$$

$$E (p e_0 + u_1) (p e_1 + u_2) = 0$$

random

$$E [\sqrt{1-\rho^2} e_1, u_2] = 0$$

where  $e_1 = \rho e_0 + u_1$  since  $E u_1 u_j = 0 \quad i \neq j$

Intuitively,  $e_1$  happens before  $u_2, \dots$ . Therefore  $u_2$  can have no effect on prior events.

Transform each equation:

$$E (P: e_i) (P_j: e_j)' = \begin{bmatrix} ? & & \\ & \Phi_{ii} & \\ & & \Phi_{jj} \\ & & & \ddots \end{bmatrix}_{T-1 \times T-1}$$

cov. between transform errors of  $i^{\text{th}}$  and  $j^{\text{th}}$  eq.

The first element  $E [\sqrt{1-\rho_i^2} e_{i1} \sqrt{1-\rho_j^2} e_{j2}] =$

$$\sqrt{1-\rho_i^2} \sqrt{1-\rho_j^2} \frac{\Phi_{ij}}{1-\rho_i \rho_j} \neq \Phi_{ij} \text{ unless } \rho_i = \rho_j$$

Eliminate 1<sup>st</sup> row of  $P$  matrix - transform system based on  $T-1$  eq for each individual.

$$E e_i = 0$$

$$E e_i e_j = \Phi_{ij} I_{T-1}$$

$$\text{Cov } e_i = \Phi_{ii} I_{T-1}$$

Only the contemporaneous correlation remains

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_T \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} \beta + \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_T \end{bmatrix}$$

$$\text{Let } \underline{\Phi} = \begin{bmatrix} \Phi_{11} & \Phi_{12} & \dots & \Phi_{1N} \\ \Phi_{21} & & & \\ \vdots & & & \\ \Phi_{N1} & & & \Phi_{NN} \end{bmatrix}$$

$$\text{Cov } e = \underline{\Phi} \otimes I_{T-1}$$

$$\tilde{\beta}_{OLS} = (X' (\underline{\Phi} \otimes I_{T-1}) X)^{-1} X' (\underline{\Phi} \otimes I_{T-1})^{-1} y$$

$$\tilde{\beta}_{FGLS} = (X' (\hat{\underline{\Phi}} \otimes I_{T-1})^{-1} X)^{-1} X' (\hat{\underline{\Phi}} \otimes I_{T-1})^{-1} y$$

$$\hat{\underline{\Phi}} = \begin{bmatrix} \hat{\Phi}_{11} & & & \\ \hat{\Phi}_{21} & \ddots & & \\ \vdots & & \ddots & \\ \hat{\Phi}_{N1} & \dots & \dots & \hat{\Phi}_{NN} \end{bmatrix}$$

$$\hat{\Phi}_{ij} = \frac{\hat{e}_{\cdot i} \hat{e}_{\cdot j}}{T-1}$$

1. OLS - calculate  $\hat{e}$  and  $\hat{\Phi}_{ij}$  for each  $i$
2. From  $\hat{\Phi}$  eliminate row 1 for each  $N$   
calculate  $\hat{e}$
3. use  $\hat{e}$  to estimate contempor. cov.  
Apply SUR.

Models where intercept varies across individuals  
(but constant for each individual over time)

$$(1) \quad y_{it} = \beta_{i0} + \sum_{k=2}^K \beta_{ik} x_{kit} + e_{it}$$

$$E(e_{it}) = 0$$

$$E(e_{it}^2) = \sigma_e^2$$

$$i = 1, \dots, n$$

$$t = 1, \dots, T$$

This model requires that we stack by individual.  
Each individual has his own intercept.

$$\begin{bmatrix} y_{11} \\ \vdots \\ y_{1T} \\ \vdots \\ y_{N1} \\ \vdots \\ y_{NT} \end{bmatrix}_{NT \times 1} = \begin{bmatrix} \beta_{i1} & 0 & \dots & 0 & 0 & X_{i1} \\ 0 & \beta_{i2} & & & & X_{i2} \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & \dots & \dots & \beta_{iT} & & X_{iT} \\ 0 & \dots & \dots & \dots & \beta_{iN} & X_{iN} \end{bmatrix}_{NT \times N+K-1} \begin{bmatrix} \beta_{11} \\ \beta_{12} \\ \vdots \\ \beta_{1N} \\ \beta_s \end{bmatrix}_{N+K-1 \times 1} + \begin{bmatrix} e_{11} \\ \vdots \\ e_{1T} \\ \vdots \\ e_{N1} \\ \vdots \\ e_{NT} \end{bmatrix}_{NT \times 1}$$

$X_i$  = observations of  $X$  for individual  $i$ .  
 $i = 1, \dots, N$ .

$$\underline{y} = \left[ \underline{I}_N \otimes \underline{J}_T \quad \vdots \quad X \right] \begin{bmatrix} \underline{\beta}_1 \\ \vdots \\ \underline{\beta}_s \end{bmatrix} + \underline{e}$$

$$\text{let } \bar{X} = \left[ \underline{I}_N \otimes \underline{J}_T \quad \vdots \quad X \right]$$

$$\underline{b} = (\bar{X}' \bar{X})^{-1} \bar{X}' \underline{y}$$

$$\underline{b} = \left[ (\underline{I}_N \otimes \underline{J}_T)' (\underline{I}_N \otimes \underline{J}_T X)' \right]^{-1} (\underline{I}_N \otimes \underline{J}_T X)' \underline{y}$$

$$\underline{b} = \left( \begin{bmatrix} (\underline{I}_N \otimes \underline{J}_T)' \\ (X)' \end{bmatrix} (\underline{I}_N \otimes \underline{J}_T X)' \right)^{-1} \begin{bmatrix} (\underline{I}_N \otimes \underline{J}_T)' \\ (X)' \end{bmatrix} \underline{y}$$

$$(\underline{I}_N \otimes \underline{J}_T)' = (\underline{I}_N' \otimes \underline{J}_T')$$

$$b_2 = \begin{bmatrix} I_N \otimes j_T j_T' & (I_N \otimes j_T)' X \\ X'(I_N \otimes j_T) & X'X \end{bmatrix}^{-1} \bar{X}' y$$

This inversion can be computationally impossible.  
We can use the partitioned inverse result to simplify matters.

$$(X'X)^{-1} = \begin{bmatrix} P & R \\ R' & Q \end{bmatrix}^{-1} = \begin{bmatrix} P^{-1} + P^{-1} R F R' P^{-1} & -P^{-1} R F \\ -F' R' P^{-1} & F \end{bmatrix}$$

$$\text{where } F \equiv [Q - R' P^{-1} R]^{-1}$$

$$b_2 = (X'X)^{-1} X' y = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{T} I_N + \frac{1}{T} (I_N \otimes j_T)' X F X' (I_N \otimes j_T) \frac{1}{T} & -\frac{1}{T} (I_N \otimes j_T)' X F \\ -F X' (I_N \otimes j_T) \frac{1}{T} & F \end{bmatrix}$$

$$F^{-1} = X'X - \frac{1}{T} X' (I_N \otimes j_T) \frac{1}{T} (I_N \otimes j_T)' X \\ X' \frac{1}{T} (I_{NT} - (I_N \otimes j_T j_T')) X$$

$$I_N \otimes I_T = I_{NT}$$

$$X' (I_N \otimes j_T - I_N \otimes \frac{j_T j_T'}{T}) X$$

$$F^{-1} = X' (I_N \otimes I_T - \frac{j_T j_T'}{T}) X = X' (I_N \otimes D_T) X \\ \text{where } D_T = I_T - \frac{j_T j_T'}{T}$$

$$\left[ -F X' (I_N \otimes j_T) \frac{1}{T} = -X' (I_N \otimes D_T) X X' (I_N \otimes j_T) \right]$$

$$b_s = -F'R'P^{-1}Xy + FXy \quad F = F'$$

$$= -FX'(I_N \otimes j_T) \frac{1}{T} (I_N \otimes j_T) y + FXy$$

$$= -FX'(I_N \otimes \frac{j_T j_T'}{T}) y + FXy$$

$$= FX(I_{NT} - I_N \otimes \frac{j_T j_T'}{T}) y = FX'(I_N \otimes I_T - I_N \otimes \frac{j_T j_T'}{T}) y$$

$$= FX'(I_N \otimes I_T - \frac{j_T j_T'}{T}) y$$

$$\tilde{b}_s = FX'(I_N \otimes D_T) y$$

$$b_s = [X'(I_N \otimes D_T)X]^{-1} X'(I_N \otimes D_T) y \quad (2)$$

note that this requires inversion of an  $(K-1 \times K-1)$  matrix.

Intercept

$$\tilde{b}_1 = \left[ \frac{1}{T} I_N + \frac{1}{T} (I_N \otimes j_T)' X F X' (I_N \otimes j_T) \frac{1}{T} \right]^{-1} (I_N \otimes j_T)' y - \frac{1}{T} (I_N \otimes j_T)' X F X' y$$

$$\tilde{b}_1 = \frac{1}{T} (I_N \otimes j_T)' y + \frac{1}{T} (I_N \otimes j_T)' X F X' (I_N \otimes \frac{j_T j_T'}{T}) y - \frac{1}{T} (I_N \otimes j_T)' X F X' y$$

First Term

$$\frac{1}{T} (I_N \otimes j_T)' y = \frac{1}{T} \begin{bmatrix} j_T' & & \\ & j_T' & \\ & & j_T' \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} j_T' y_1 \\ j_T' y_2 \\ \vdots \\ j_T' y_n \end{bmatrix} = \begin{bmatrix} \bar{y}_1 \\ \bar{y}_2 \\ \vdots \\ \bar{y}_n \end{bmatrix} = \bar{y}_i$$

$\bar{y}_i$  is Average over the  $i^{\text{th}}$  individual.

likewise, in the next 2 terms

$$\frac{1}{T} (I_n \otimes j_T)' X =$$

$$\frac{1}{T} \begin{bmatrix} j_T' \\ j_T' \\ \vdots \\ j_T' \end{bmatrix} X =$$

$$\begin{bmatrix} \bar{X}_{1.}' \\ \bar{X}_{2.}' \\ \vdots \\ \bar{X}_{n.}' \end{bmatrix} = \bar{X}_0' \\ (n \times (k-1))$$

$$b_1 = \bar{y}_0 + \bar{X}_0' F X (I_n \otimes j_T) y \\ - \bar{X}_0' F X y$$

$$= \bar{y}_0 - \bar{X}_0' \left[ -F X (I_n \otimes j_T) y + F X y \right]$$

$$b_1 = \bar{y}_0 - \bar{X}_0' b_s$$

Properties of  $D_T$

(i)  $D_T$  is symmetric

$$D_T = D_T'$$

(ii)  $D_T$  is Idempotent

$$D_T \cdot D_T = D_T$$

If  $D_T$  is (i) and (ii) then so is  $(I_n \otimes D_T)$ .  $\square$

$$b_s = \left[ X' (I_n \otimes D_T) (I_n \otimes D_T) X \right]^{-1} X' (I_n \otimes D_T) (I_n \otimes D_T) y$$

$(W'W)^{-1}W'Z$  as like in the book

$$(Z'Z)^{-1}Z'W$$

$$Z \equiv (I_n \otimes D_T) X$$

$$W \equiv (I_n \otimes D_T) y$$

Multiplication of Any vector by  $D_T$  is equivalent to putting it in deviation form.

$$D_T \underline{y}_i = \left[ I_T - \frac{j_T j_T'}{T} \right] \underline{y}_i = \underline{y}_i - \frac{j_T j_T'}{T} \underline{y}_i$$

$$= \underline{y}_i - \frac{j_T \bar{y}_i}{T}$$

Transform the model using  $(I_N \otimes D_T)$

$$(I_N \otimes D_T) y = (I_N \otimes D_T) X \beta + (I_N \otimes D_T) e$$

$$W = \left[ I_N \otimes D_T \right] \left[ I_N \otimes j_T : X_0 \right] \beta + 1 e$$

$$= I_N \otimes D_T j_T \quad (I_N \otimes D_T) X_0$$

$$\left( I_T - \frac{j_T j_T'}{T} \right) j_T = j_T - \frac{j_T \cdot T}{T} = 0 \quad \therefore$$

$$W = Z \beta + e^* \quad \text{where } e^* = (I_N \otimes D_T) e$$

Within Estimator becomes

$$\hat{\beta} = (Z' Z)^{-1} Z' W$$

Everything else is obtained as always

$$\hat{e} = y - X \begin{bmatrix} b_1 \\ \vdots \\ b_k \end{bmatrix} \quad \hat{\sigma}^2 = \frac{\hat{e}' \hat{e}}{NT - N + k - 1}$$

Model: Constant Slopes, Individual difference  
 where individuals represent a random sample.

### Error Components

$$y_{it} = \beta_{1i} + \sum_{k=2}^K \beta_k x_{ikt} + e_{it}$$

$$i = 1, \dots, n$$

$$t = 1, \dots, T.$$

$\beta_{1i}$  is now random

$$E(\beta_{1i}) = \bar{\beta}_1$$

$$\text{Var}(\beta_{1i}) = \sigma_u^2$$

$$\beta_{1i} = \bar{\beta}_1 + u_i$$

$$E u_i = 0$$

$$\text{Var}(u_i) = \sigma_u^2$$

$$E u_i u_j = 0$$

$$E u_{it}, u_{is} = 0 \quad t \neq s$$

### $i^{\text{th}}$ Individual

$$y_i = x_i \beta + (u_i j_T + e_i)$$

$$E(u_i j_T + e_i) = 0$$

$$E(u_i j_T + e_i)(u_i j_T + e_i)' =$$

$$= E(u_i j_T j_T' u_i' + u_i j_T e_i' + e_i j_T' u_i' + e_i e_i')$$

$$\sigma_u^2 j_T j_T' + 0 + 0 + \sigma_e^2 I_T$$

Implications

1. homoskedastic with  $\sigma_u^2 + \sigma_e^2$  on diagonal elements
2. "serial correlation"  $\sigma_u^2$  is same for each time (for  $i$ ).

## Complete Model

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix} \beta + \begin{matrix} u_{1j_1} \\ \vdots \\ u_{Nj_T} \end{matrix} + \begin{matrix} e_1 \\ \vdots \\ e_N \end{matrix}$$

$$\underline{y} = X \underline{\beta} + \underline{u} \otimes \underline{j}_T + \underline{e}$$

$$\begin{aligned} \text{COV MATRIX} &= E(\underline{u} \otimes \underline{j}_T + \underline{e})(\underline{u} \otimes \underline{j}_T + \underline{e})' \\ &= \sigma_u^2 I_N \otimes \underline{j}_T \underline{j}_T' + \sigma_e^2 I_{NT} \\ &= \sigma_u^2 I_N \otimes \underline{j}_T \underline{j}_T' + \sigma_e^2 I_N \otimes I_T \\ &= I_N \otimes [\sigma_u^2 \underline{j}_T \underline{j}_T' + \sigma_e^2 I_T] \end{aligned}$$

$$\underline{\Phi} = I_N \otimes V_{T \times T}$$

The idea now, is to find a matrix (nonsing)  $P$  that diagonalizes the covariance matrix

$$P \underline{\Phi} P' = \sigma_e^2 I_{NT}$$

$$P = I_N \otimes P^*$$

$$P^* = I_T - \left(1 - \frac{\sigma_e}{\sigma_u}\right) \frac{\underline{j}_T \underline{j}_T'}{T}$$

$$\sigma_i^2 = T \sigma_u^2 + \sigma_e^2$$

$$\alpha \in [0, 1)$$

since if  $\sigma_u^2 = 0$  - no indiv diff  
then  $\sigma_i^2 = \sigma_e^2 \Rightarrow P^* = I_T$

## Hilkeith Houch Random Coefficient Model

This type of model is reasonable when we have cross sectional data on a number of micro-units.

$$J_t = \sum_{k=1}^K \beta_{tk} \gamma_{tk}$$

$\beta$  varies with each individual.

$$\beta_{tk} = \bar{\beta}_k + v_{tk} \quad k=1, \dots, K.$$

$\bar{\beta}_k$  = mean effect

$v_{tk}$  = individual effect

What this amounts to is error components for slopes.

$$v_{tk} : \quad E(v_{tk}) = 0 \\ \text{Var}(v_{tk}) = \sigma_k^2$$

could make other covariance assumptions like presence of serial correlation + autocor. etc.

$$\begin{aligned} y_t &= \sum_{k=1}^K (\bar{\beta}_k + v_{tk}) \gamma_{tk} \\ &= \sum_{k=1}^K \bar{\beta}_k \gamma_{tk} + \sum_{k=1}^K v_{tk} \gamma_{tk} \\ &= \gamma_t' \beta + \gamma_t' v_t \end{aligned}$$

since one column of  $\gamma_t$  is = 1

$$\sum_{k=1}^K v_{tk} \gamma_{tk} = v_{t1} + \sum_{k=2}^K v_{tk} \gamma_{tk}$$

$v_{t1}$  captures variability of intercept + overall variance in equation. Presence of  $\epsilon$  would be irrelevant.

$$E \Psi_t' V_t = 0$$

$$E \Psi_t' V_t V_t' \Psi_t = \Psi_t' \text{Cov}(V_t) \Psi_t$$

$$\text{Cov}(V_t) = \begin{bmatrix} \alpha_1^2 & & & \\ & \alpha_2^2 & & \\ & & \ddots & \\ 0 & & & \alpha_k^2 \end{bmatrix}$$

if  $E V_t V_t' \neq 0$   $t \neq s$  then off diag elements are filled.

$$\begin{aligned} \text{Var } \Psi_t' V_t &= \Psi_t' \Sigma \Psi_t = 1 \cdot \alpha_1^2 + \Psi_{t2}^2 \alpha_2^2 + \dots + \Psi_{tk}^2 \alpha_k^2 \\ &= \begin{bmatrix} 1 & \Psi_{t2}^2 & \Psi_{t3}^2 & \dots & \Psi_{tk}^2 \end{bmatrix} \begin{bmatrix} \alpha_1^2 \\ \alpha_2^2 \\ \vdots \\ \alpha_k^2 \end{bmatrix} \\ &= Z_t' \alpha \end{aligned}$$

$\alpha$  can be estimated as

$$\hat{\alpha} = (F'F)^{-1} F' \hat{e}$$

$$F = MZ \quad M = (I - X(X'X)^{-1}X')$$

$$\hat{e} = My = Me$$

$$\hat{e} = \hat{M}y$$

Proof:

$$\hat{e} = Me$$

$$\text{Cov } \hat{e} = M \Phi M$$

$$\text{Cov}(\hat{e}) = \begin{bmatrix} E \hat{e} \hat{e}' & 0 \\ 0 & \dots \end{bmatrix}$$

$$E \hat{e} \hat{e}' = \begin{bmatrix} M_t & 0 \\ 0 & M_t \end{bmatrix} = M_t' \alpha_t^2$$

$$E \dot{c} = \dot{M} z \alpha$$

$$\dot{c} = \dot{M} z \alpha + u$$

apply OLS

$$[\dot{M} z]' [\dot{M} z]^{-1} (\dot{M} z)' \dot{c} = \hat{\alpha}$$