

# PANEL DATA Models

Some BASIC considerations [CT, p. 230]

(1) Usually observed AT regular intervals in time. - There are some exceptions, though.

(2) BALANCED  $T_i = T$  for all  $i$   
- no missing time observations for ANY individual. sample size =  $NT$

UNBALANCED AT least 1 missing time obs for a subset of individuals

SAMPLE SIZE  $< NT$

(3) small  $N$  - long  $T$

large  $N$  - short  $T$

large  $N$  - large  $T$

The distinction is important for estimation and inference

(4) Model errors are likely correlated

units =  
Individuals

Usually, we expect errors for a unit ( $i$ ) to be correlated.

The units may be uncorrelated with one another though.

⇒ "CLUSTER"

units =

Countries  
States, etc

It is also possible that

there may be correlation across individuals. Macro events could affect all countries.

Either way, GLS or some robust cov. estimation is required to get consistent SE errors, tests, and C.I.

(5) Identification depends on type of regressor

(a) time invariant regressors e.g.,  
gender, race may not be estimable.

(b) time trends won't vary by individual. - a macro effects.

(6) Some coeffs may vary across individual and/or time.

(7) Fixed effects estimation is used a lot in Econ

Because endogenous regressors can be used if they are correlated only with the individual's time-invariant characteristics.

Many other disciplines rely on random effects, which are often inconsistent if regressors are not completely exogenous.

(8) Dynamic panels are sometimes estimated. — They include lagged dependent variables as regressors.

# Basic Panel Models

Individual effect.

$$y_{it} = \alpha_i + \underset{\sim}{\gamma}_{it}^T \underset{\sim}{\beta} + u_{it}$$

$$i = 1, \dots, N$$

$$t = 1, \dots, T$$

$$\underset{\sim}{\gamma}_{it}^T = \{ \gamma_{2it} \ \gamma_{3it} \ \dots \ \gamma_{k_{it}} \}$$

$$\underset{\sim}{\beta} = ( \dots, \beta_2, \dots, \beta_k )$$

$\alpha_i$  individual effect.  
time-invariant.

Here, The individual effect can be correlated with the variables in  $\gamma_{it}$ . ~~this is~~ Basically, you have a parameter,  $\alpha_i$ , to estimate for each individual (fixed)

It assumes that

$$E[\mu_{it} | \alpha_i, \gamma_{it}] = 0$$

Random Effects

$\alpha_i \sim (0, \sigma_\alpha^2)$  is random and unobservable

$$y_{it} = \gamma_{it}^T \beta + \bar{\beta}_i + \epsilon_{it}$$

$$\epsilon_{it} = (\mu_{it} + \alpha_i)$$

$\alpha_i$ , being random, cannot be correlated with  $\gamma_{it}$  in this case. However, you can estimate parameters and ME for time-invariant regressors.

Pooled or Population Averaged

$$y_{it} = \alpha + \gamma_{it}^T \beta + \mu_{it}$$

is consistent as long as individual effects (in  $\mu_{it}$ ) are NOT correlated with  $\gamma_{it}$

6

with this one, you'll want to  
use "cluster" std errors since  
it is likely that errors within  
an individual unit are correlated.

### Two-way fixed Effects

$$y_{it} = \alpha_i + \gamma_t + \gamma_{it}^T \beta + u_{it}$$

time dummies (drop 1)  
+ individual dummies (no const in  $\gamma_{it}$ )

### Mixed Linear Models

$$y_{it} = \alpha_i + \gamma_{it}^T \beta_i + u_{it}$$

$$(\alpha_i, \beta_i^T)^T \sim (\beta, \Sigma)$$

For long panels, you would  
be separate regressions for  
each  $i$ .